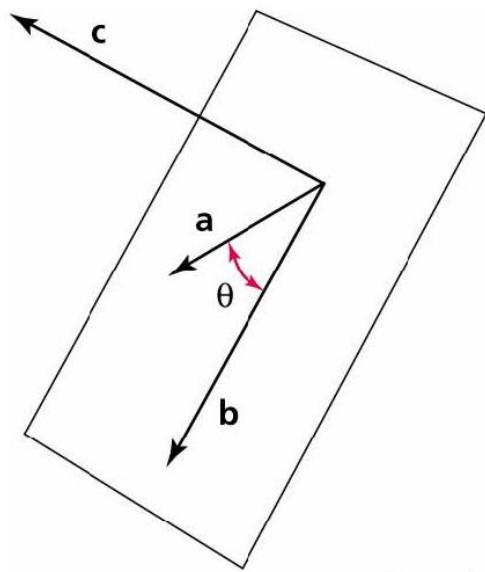


Find a vector perpendicular to two given vectors



$$\vec{\tau} = \vec{r} \times \vec{F}$$

$$\vec{L} = \vec{r} \times \vec{p}$$

Torque and Angular Momentum

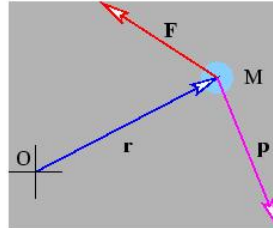
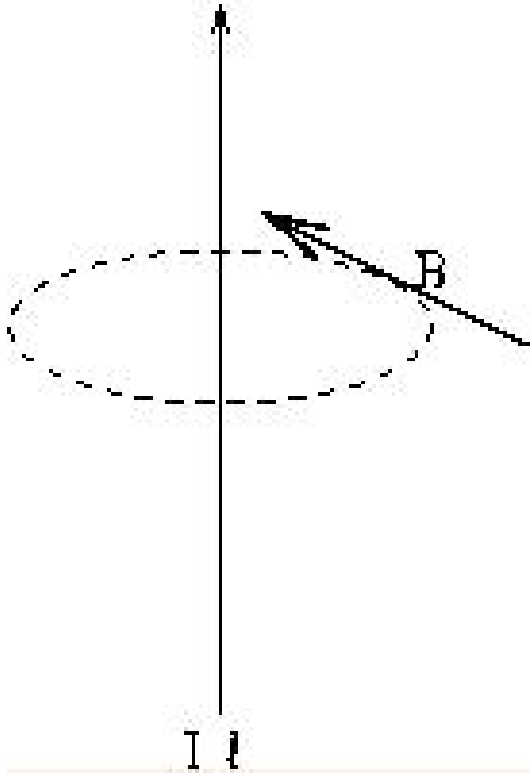
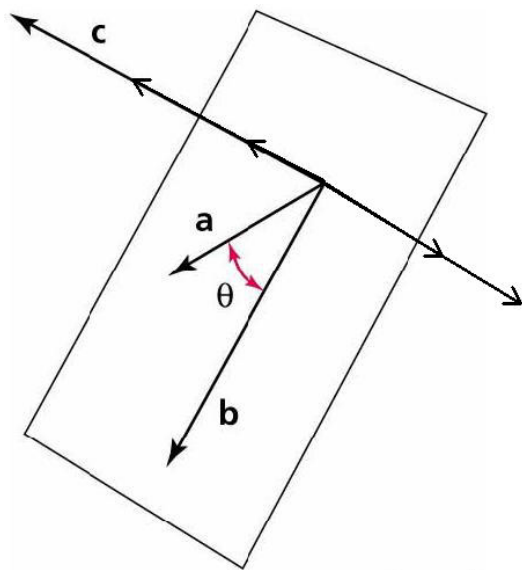


Figure 11.2: A mass M located at $\mathbf{r}$ relative to the origin O has momentum $\mathbf{p}$ and has a force $\mathbf{F}$ applied to it. By the right-hand rule the torque $\boldsymbol{\tau} = \mathbf{r} \times \mathbf{F}$ points out of the page, while the angular momentum $\mathbf{L} = \mathbf{r} \times \mathbf{p}$ points into the page.

$$\vec{\mathbf{F}}_B = q\vec{\mathbf{v}} \times \vec{\mathbf{B}}$$



There are many vectors perpendicular to two given vectors.



Find a vector $\vec{\mathbf{w}} = \langle w_1, w_2, w_3 \rangle$ that is perpendicular to both $\vec{\mathbf{x}} = \langle x_1, x_2, x_3 \rangle$ and $\vec{\mathbf{y}} = \langle y_1, y_2, y_3 \rangle$

$$\vec{\mathbf{x}} \bullet \vec{\mathbf{w}} = 0 \qquad \vec{\mathbf{y}} \bullet \vec{\mathbf{w}} = 0$$

$$\vec{\mathbf{x}} \bullet \vec{\mathbf{w}} = 0 \qquad \vec{\mathbf{y}} \bullet \vec{\mathbf{w}} = 0$$

$$x_1w_1 + x_2w_2 + x_3w_3 = 0$$

$$y_1w_1 + y_2w_2 + y_3w_3 = 0$$

$$x_1w_1 + x_2w_2 + x_3w_3 = 0$$

$$y_1w_1 + y_2w_2 + y_3w_3 = 0$$

$$x_1w_1 + x_2w_2 = -x_3w_3$$

$$y_1w_1 + y_2w_2 = -y_3w_3$$

$$x_1w_1 + x_2w_2 = -x_3w_3$$

$$y_1w_1 + y_2w_2 = -y_3w_3$$

Solve for w_1 and w_2 in terms of w_3

$$w_1 = \frac{(x_2y_3 - x_3y_2)}{(x_1y_2 - y_1x_2)}w_3$$

$$w_2 = \frac{(x_1y_3 - x_3y_1)}{(y_1x_2 - x_1y_2)}w_3$$

$$x_1w_1 + x_2w_2 = -x_3w_3$$

$$y_1w_1 + y_2w_2 = -y_3w_3$$

Solve for w_1 and w_2 in terms of w_3

$$w_1 = \frac{(x_2y_3 - x_3y_2)}{(x_1y_2 - y_1x_2)}w_3$$

$$w_2 = -\frac{(x_1y_3 - x_3y_1)}{(x_1y_2 - y_1x_2)}w_3$$

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$

$$w_1 = \frac{(x_2y_3 - x_3y_2)}{(x_1y_2 - y_1x_2)}w_3 = \frac{\begin{vmatrix} x_2 & x_3 \\ y_2 & y_3 \end{vmatrix}}{\begin{vmatrix} x_1 & x_2 \\ y_1 & y_2 \end{vmatrix}}w_3$$

$$w_2 = -\frac{(x_1y_3 - x_3y_1)}{(x_1y_2 - y_1x_2)}w_3 = -\frac{\begin{vmatrix} x_1 & x_3 \\ y_1 & y_3 \end{vmatrix}}{\begin{vmatrix} x_1 & x_2 \\ y_1 & y_2 \end{vmatrix}}w_3$$

$$w_1 = \frac{\begin{vmatrix} x_2 & x_3 \\ y_2 & y_3 \end{vmatrix}}{\begin{vmatrix} x_1 & x_2 \\ y_1 & y_2 \end{vmatrix}} w_3 \qquad w_2 = -\frac{\begin{vmatrix} x_1 & x_3 \\ y_1 & y_3 \end{vmatrix}}{\begin{vmatrix} x_1 & x_2 \\ y_1 & y_2 \end{vmatrix}} w_3$$

For simplicity, take $w_3 = \begin{vmatrix} x_1 & x_2 \\ y_1 & y_2 \end{vmatrix}$

$$w_1 = \begin{vmatrix} x_2 & x_3 \\ y_2 & y_3 \end{vmatrix} \qquad w_2 = - \begin{vmatrix} x_1 & x_3 \\ y_1 & y_3 \end{vmatrix} \qquad w_3 = \begin{vmatrix} x_1 & x_2 \\ y_1 & y_2 \end{vmatrix}$$

$$\begin{aligned}\vec{\mathbf{w}} &= w_1\vec{\mathbf{i}} + w_2\vec{\mathbf{j}} + w_3\vec{\mathbf{k}} \\ &= \begin{vmatrix} x_2 & x_3 \\ y_2 & y_3 \end{vmatrix} \vec{\mathbf{i}} - \begin{vmatrix} x_1 & x_3 \\ y_1 & y_3 \end{vmatrix} \vec{\mathbf{j}} + \begin{vmatrix} x_1 & x_2 \\ y_1 & y_2 \end{vmatrix} \vec{\mathbf{k}}\end{aligned}$$

$$\begin{aligned}
\vec{\mathbf{w}} &= w_1 \vec{\mathbf{i}} + w_2 \vec{\mathbf{j}} + w_3 \vec{\mathbf{k}} \\
&= \begin{vmatrix} x_2 & x_3 \\ y_2 & y_3 \end{vmatrix} \vec{\mathbf{i}} - \begin{vmatrix} x_1 & x_3 \\ y_1 & y_3 \end{vmatrix} \vec{\mathbf{j}} + \begin{vmatrix} x_1 & x_2 \\ y_1 & y_2 \end{vmatrix} \vec{\mathbf{k}} \\
&= \begin{vmatrix} \vec{\mathbf{i}} & \vec{\mathbf{j}} & \vec{\mathbf{k}} \\ x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \end{vmatrix} \\
&= \vec{\mathbf{x}} \times \vec{\mathbf{y}}
\end{aligned}$$

Example: Find a vector that is perpendicular to both of the following vectors:

$$\vec{\mathbf{u}} = \langle 1, 2, 1 \rangle \quad \vec{\mathbf{v}} = \langle 0, -1, 2 \rangle$$

Calculate $\vec{\mathbf{u}} \times \vec{\mathbf{v}}$

$$\mathbf{u} \times \mathbf{v} = \begin{vmatrix} \textcircled{\mathbf{i}} & \textcircled{\mathbf{j}} & \textcircled{\mathbf{k}} \\ 1 & 2 & 1 \\ 0 & -1 & 2 \end{vmatrix} - \begin{vmatrix} \textcircled{\mathbf{i}} & \textcircled{\mathbf{j}} & \textcircled{\mathbf{k}} \\ 1 & 2 & 1 \\ 0 & -1 & 2 \end{vmatrix} + \begin{vmatrix} \textcircled{\mathbf{i}} & \textcircled{\mathbf{j}} & \textcircled{\mathbf{k}} \\ 1 & 2 & 1 \\ 0 & -1 & 2 \end{vmatrix}$$

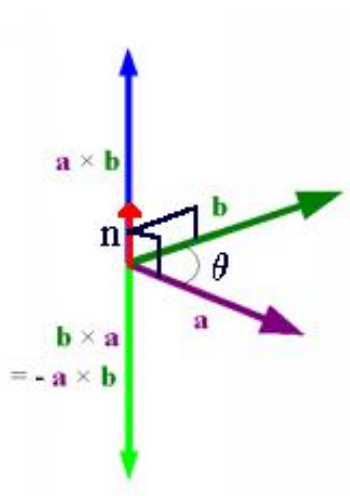
$$\begin{aligned} \vec{\mathbf{u}} \times \vec{\mathbf{v}} &= \begin{vmatrix} \vec{\mathbf{i}} & \vec{\mathbf{j}} & \vec{\mathbf{k}} \\ 1 & 2 & 1 \\ 0 & -1 & 2 \end{vmatrix} \\ &= \begin{vmatrix} 2 & 1 \\ -1 & 2 \end{vmatrix} \vec{\mathbf{i}} - \begin{vmatrix} 1 & 1 \\ 0 & 2 \end{vmatrix} \vec{\mathbf{j}} + \begin{vmatrix} 1 & 2 \\ 0 & -1 \end{vmatrix} \vec{\mathbf{k}} \\ &= 5\vec{\mathbf{i}} - 2\vec{\mathbf{j}} - \vec{\mathbf{k}} \\ &= \langle 5, -2, -1 \rangle \end{aligned}$$

$$\vec{\mathbf{u}} \times \vec{\mathbf{v}} = \langle 5, -2, -1 \rangle$$

Compare with:

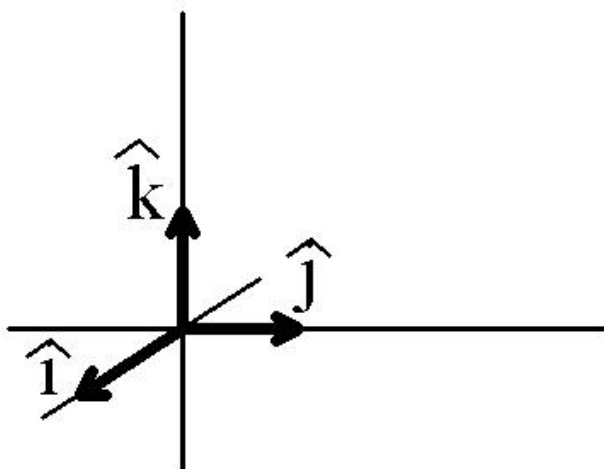
$$\vec{\mathbf{v}} \times \vec{\mathbf{u}} = \begin{vmatrix} \vec{\mathbf{i}} & \vec{\mathbf{j}} & \vec{\mathbf{k}} \\ 0 & -1 & 2 \\ 1 & 2 & 1 \end{vmatrix} = \langle -5, 2, 1 \rangle$$

The cross product is not commutative

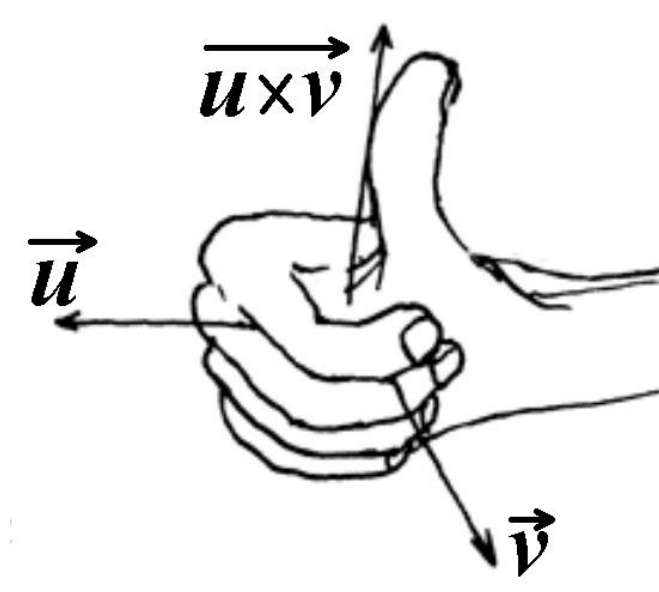


$$\vec{\mathbf{i}} \times \vec{\mathbf{j}} = \begin{vmatrix} \vec{\mathbf{i}} & \vec{\mathbf{j}} & \vec{\mathbf{k}} \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{vmatrix} = \begin{vmatrix} 0 & 0 \\ 1 & 0 \end{vmatrix} \vec{\mathbf{i}} - \begin{vmatrix} 1 & 0 \\ 0 & 0 \end{vmatrix} \vec{\mathbf{j}} + \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} \vec{\mathbf{k}} = \vec{\mathbf{k}}$$

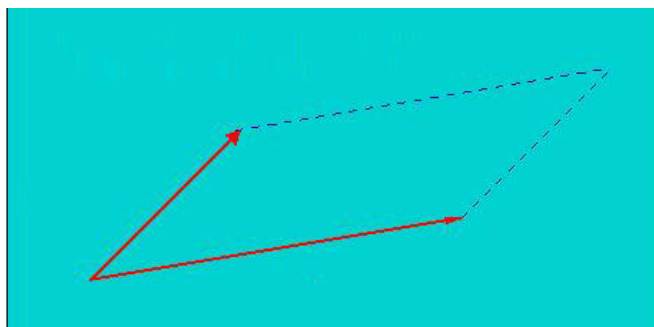
$$\vec{i} \times \vec{j} = \vec{k} \quad \vec{j} \times \vec{k} = \vec{i} \quad \vec{k} \times \vec{i} = \vec{j}$$



The Right Hand Rule

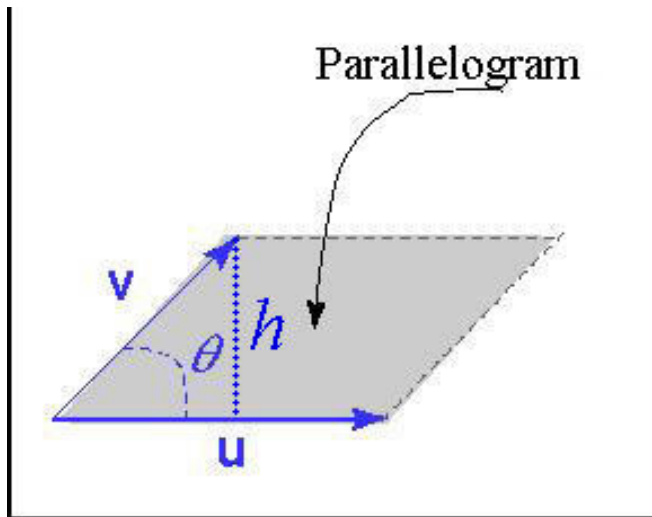


Two vectors form the edges of a parallelogram

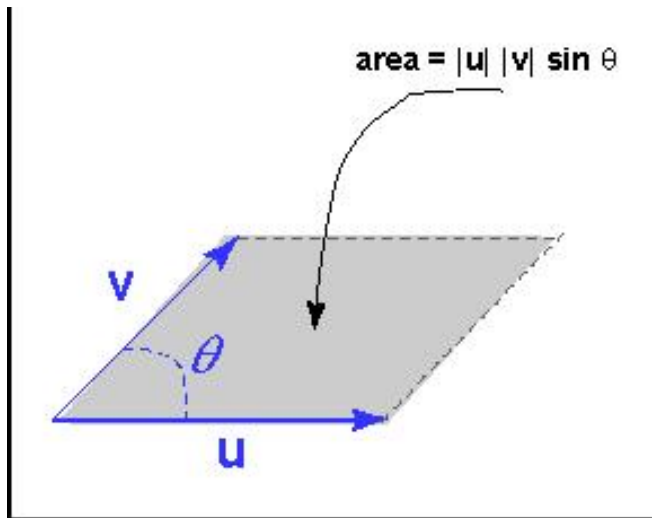


$$\text{Area} = h\|\vec{\mathbf{u}}\|$$

$$h = \|\vec{\mathbf{v}}\| \sin \theta$$

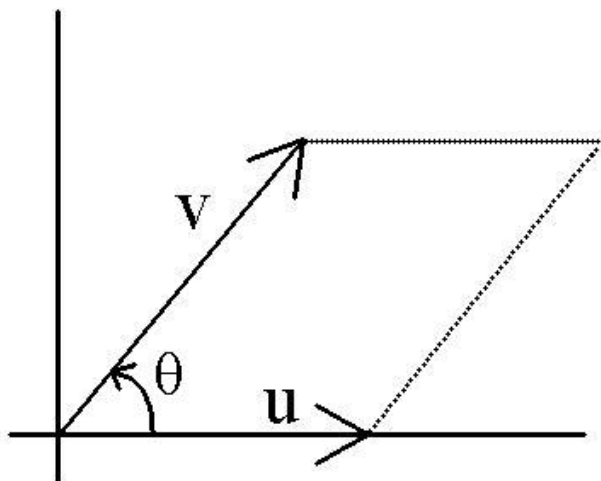


$$\text{Area} = h\|\vec{u}\| = \|\vec{u}\|\|\vec{v}\|\sin\theta$$



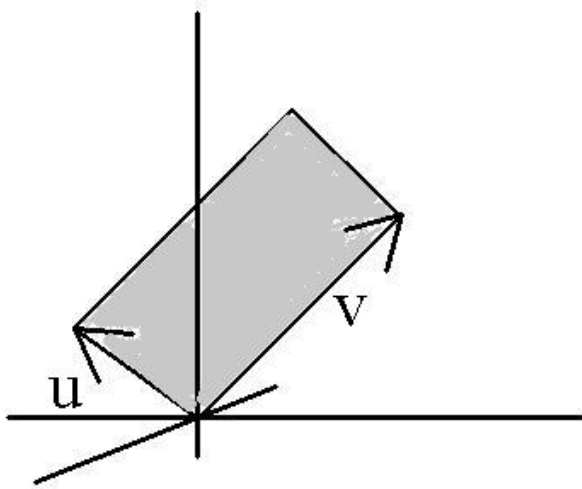
Suppose $\|u\| = a$ and $\|v\| = b$

$$\vec{\mathbf{u}} = \langle a, 0, 0 \rangle \quad \vec{\mathbf{v}} = \langle b \cos \theta, b \sin \theta, 0 \rangle$$



$$\vec{\mathbf{u}} \times \vec{\mathbf{v}} = \begin{vmatrix} \vec{\mathbf{i}} & \vec{\mathbf{j}} & \vec{\mathbf{k}} \\ a & 0 & 0 \\ b \cos \theta & b \sin \theta & 0 \end{vmatrix} = (ab \sin \theta) \vec{\mathbf{k}} = (\|u\| \|v\| \sin \theta) \vec{\mathbf{k}}$$

Find the area of the parallelogram

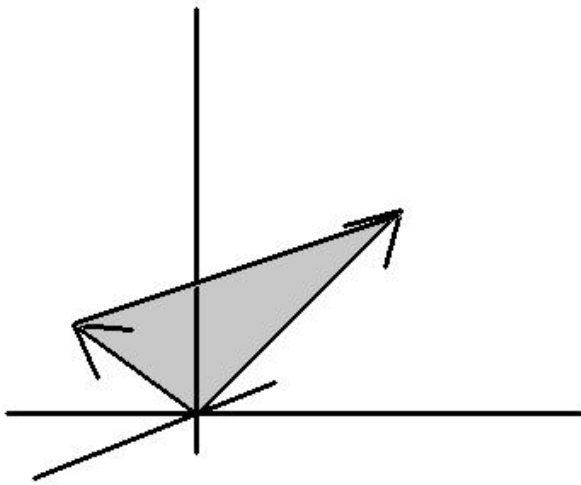


$$\vec{\mathbf{u}} = \langle 1, 0, 1 \rangle \quad \vec{\mathbf{v}} = \langle 0, 2, 2 \rangle$$

$$\vec{\mathbf{u}} \times \vec{\mathbf{v}} = \begin{vmatrix} \vec{\mathbf{i}} & \vec{\mathbf{j}} & \vec{\mathbf{k}} \\ 1 & 0 & 1 \\ 0 & 2 & 2 \end{vmatrix} = -2\vec{\mathbf{i}} - 2\vec{\mathbf{j}} + 2\vec{\mathbf{k}}$$

$$\|\vec{\mathbf{u}} \times \vec{\mathbf{v}}\| = \sqrt{4 + 4 + 4} = \sqrt{12} = 2\sqrt{3}$$

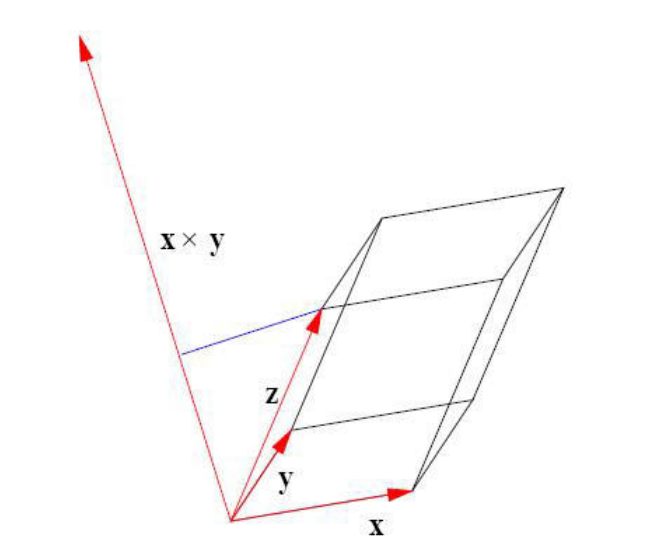
Find the area of the triangle



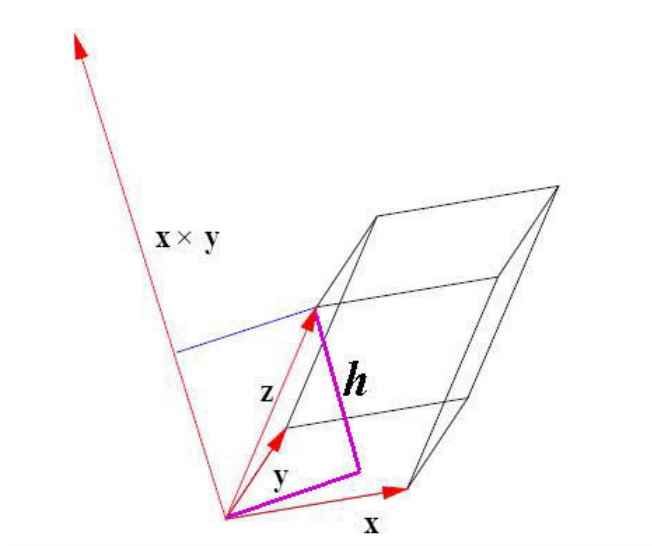
$$\vec{u} = \langle 1, 0, 1 \rangle \quad \vec{v} = \langle 0, 2, 2 \rangle$$

$$\text{Area of Triangle} = \frac{1}{2}(\text{Area of parallelogram}) = \frac{1}{2} \cdot 2\sqrt{3} = \sqrt{3}$$

The volume of a parallelepiped is related to the cross product



The volume is the altitude times the area of the base



$$\text{Volume} = h \cdot (\text{Area of base parallelogram}) = h \|\vec{\mathbf{x}} \times \vec{\mathbf{y}}\|$$

$$h = \vec{\mathbf{z}} \bullet \frac{\vec{\mathbf{x}} \times \vec{\mathbf{y}}}{\|\vec{\mathbf{x}} \times \vec{\mathbf{y}}\|}$$

$$\text{Volume} = \vec{\mathbf{z}} \bullet \frac{\vec{\mathbf{x}} \times \vec{\mathbf{y}}}{\|\vec{\mathbf{x}} \times \vec{\mathbf{y}}\|} \|\vec{\mathbf{x}} \times \vec{\mathbf{y}}\| = \vec{\mathbf{z}} \bullet (\vec{\mathbf{x}} \times \vec{\mathbf{y}})$$

$$\text{Volume} = \vec{z} \bullet (\vec{x} \times \vec{y})$$

