Assignment 20. Eigenvalues, Eigenvectors and Matrix Differential Equations

(1) For each of the following matrices, calculate all eigenvalues and corresponding eigenvectors.

$$a \qquad \begin{pmatrix} 1 & 0 \\ 2 & 3 \end{pmatrix}$$

$$det(A - \lambda I) = (1 - \lambda)(3 - \lambda) = 0 \text{ when } \lambda = 1, 3$$
For $\lambda = 1$, the eigenvector is $\begin{pmatrix} 1 \\ -1 \end{pmatrix}$
For $\lambda = 3$, the eigenvector is $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$$b \qquad \begin{pmatrix} -1 & 4 \\ 1 & -4 \end{pmatrix}$$

$$det(A - \lambda I) = \lambda(\lambda + 5) = 0 \text{ when } \lambda = 0, -5$$
For $\lambda = 0$, the eigenvector is $\begin{pmatrix} 4 \\ 1 \end{pmatrix}$
For $\lambda = -5$, the eigenvector is $\begin{pmatrix} 1 \\ -1 \end{pmatrix}$

$$c \qquad \begin{pmatrix} 3 & 2 & 0 \\ 4 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

$$det(A - \lambda I) = (2 - \lambda)(\lambda - 5)(\lambda + 1) = 0 \text{ when } \lambda = -1, 2, 5$$
For $\lambda = -1$, the eigenvector is $\begin{pmatrix} 1 \\ -2 \\ 0 \end{pmatrix}$
For $\lambda = 2$, the eigenvector is $\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$
For $\lambda = 5$, the eigenvector is $\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$

$$d \qquad \begin{pmatrix} 0 & 1 & -5 \\ 0 & 2 & -5 \\ 0 & 0 & -3 \end{pmatrix}$$

$$det(A - \lambda I) = \lambda(2 - \lambda)(\lambda + 3) = 0 \text{ when } \lambda = 0, 2, -3$$

For $\lambda = 0$, the eigenvector is $\begin{pmatrix} 1\\0\\0 \end{pmatrix}$ For $\lambda = 2$, the eigenvector is $\begin{pmatrix} 1\\2\\0 \end{pmatrix}$
For $\lambda = -3$, the eigenvector is $\begin{pmatrix} 4\\3\\3 \end{pmatrix}$

(2) Find the general solution of the differential equation

$$\frac{d\vec{\mathbf{x}}}{dt} = A\vec{\mathbf{x}} \qquad \text{where} \quad A = \begin{pmatrix} 4 & 0 \\ 0 & 3 \end{pmatrix} \quad \text{and} \quad \vec{\mathbf{x}} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\vec{\mathbf{x}} = \begin{pmatrix} c_1 e^{4t} \\ c_2 e^{3t} \end{pmatrix} = c_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} e^{4t} + c_2 \begin{pmatrix} 0 \\ 1 \end{pmatrix} e^{3t}$$

(3) Find the general solution of the differential equation

$$\frac{d\vec{\mathbf{x}}}{dt} = A\vec{\mathbf{x}} \quad \text{where} \quad A = \begin{pmatrix} 1 & 3\\ 3 & 1 \end{pmatrix} \quad \text{and} \quad \vec{\mathbf{x}} = \begin{pmatrix} x_1\\ x_2 \end{pmatrix}$$
$$det(A - \lambda I) = (\lambda - 4)(\lambda + 2) = 0 \text{ when } \lambda = 4, -2$$
For $\lambda = 4$, the eigenvector is $\begin{pmatrix} 1\\ 1 \end{pmatrix}$ For $\lambda = -2$, the eigenvector is $\begin{pmatrix} 1\\ -1 \end{pmatrix}$
$$\vec{\mathbf{x}}(t) = c_1 \begin{pmatrix} 1\\ 1 \end{pmatrix} e^{4t} + c_2 \begin{pmatrix} 1\\ -1 \end{pmatrix} e^{-2t}$$

(4) Find the solution of the differential equation

$$\frac{d\vec{\mathbf{x}}}{dt} = A\vec{\mathbf{x}} \qquad \vec{\mathbf{x}}(0) = \begin{pmatrix} 1\\0 \end{pmatrix}$$
where $A = \begin{pmatrix} -7 & 24\\-2 & 7 \end{pmatrix}$ and $\vec{\mathbf{x}} = \begin{pmatrix} x_1\\x_2 \end{pmatrix}$
 $det(A - \lambda I) = (\lambda - 1)(\lambda + 1) = 0$ when $\lambda = 1, -1$
For $\lambda = 1$, the eigenvector is $\begin{pmatrix} 3\\1 \end{pmatrix}$ For $\lambda = -1$, the eigenvector is $\begin{pmatrix} 4\\1 \end{pmatrix}$
 $\vec{\mathbf{x}}(t) = c_1 \begin{pmatrix} 3\\1 \end{pmatrix} e^t + c_2 \begin{pmatrix} 4\\1 \end{pmatrix} e^{-t}$

The initial condition implies $c_1 = -1$ and $c_2 = 1$

$$\vec{\mathbf{x}}(t) = -\begin{pmatrix} 3\\1 \end{pmatrix} e^t + \begin{pmatrix} 4\\1 \end{pmatrix} e^{-t}$$

(5) Convert the ordinary differential equation

$$y'' - 4y' + 3y = 0$$

to a matrix differential of the form

$$\frac{d\vec{\mathbf{x}}}{dt} = A\vec{\mathbf{x}}$$

Solve the matrix differential equation.

Let
$$\vec{\mathbf{x}}(t) = \begin{pmatrix} y \\ y' \end{pmatrix}$$

 $\frac{d\vec{\mathbf{x}}}{dt} = \begin{pmatrix} 0 & 1 \\ -3 & 4 \end{pmatrix} \vec{\mathbf{x}}$
 $det(A - \lambda I) = (\lambda - 1)(\lambda - 3) = 0$ when $\lambda = 1, 3$
For $\lambda = 1$, the eigenvector is $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$ For $\lambda = 3$, the eigenvector is $\begin{pmatrix} 1 \\ 3 \end{pmatrix}$
 $\vec{\mathbf{x}}(t) = c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^t + c_2 \begin{pmatrix} 1 \\ 3 \end{pmatrix} e^{3t}$

y(t) is the first coordinate of $\vec{\mathbf{x}}(t)$, so $y(t) = c_1 e^t + c_2 e^{3t}$